

BACHELOR OF TECHNOLOGY (C.B.C.S.) (2021-COURSE)
B. Tech. Sem - I COMPUTER :SUMMER- 2022
SUBJECT : MATHEMATICS FOR COMPUTING-I

Day : Monday
Date : 18-07-2022

S-24005-2022

Time : 10:00 AM-01:00 PM
Max. Marks : 60

N.B.:

- 1) All questions are **COMPULSORY**.
- 2) Figures to the right indicate **FULL** marks.
- 3) Draw neat labelled diagrams **WHEREVER** necessary.
- 4) Use of non- programmable **CALCULATOR** is allowed.

Q.1 Reduce the Matrix $A = \begin{bmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 6 \\ 4 & 5 & 6 & 7 \\ 9 & 10 & 11 & 12 \end{bmatrix}$ (10)

to an echelon form and further reduce A to its row canonical form.

OR

Q.1 Find LU factorization of $A = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 3 & 3 \\ -3 & -10 & 2 \end{bmatrix}$ (10)

Q.2 Find a subset of u_1, u_2, u_3 that gives a basis for $w = \text{span}(u_i)$ of R^5 , where (10)
 $u_1 = (1, -2, 1, 3, -1), u_2 = (-2, 4, -2, -6, 2)$
 $u_3 = (1, -3, 1, 2, 1), u_4 = (3, -7, 3, 8, -1)$

OR

Q.2 Find the dimension and basis for the subspace W of $P_3(t)$ spanned by (10)
 $u = t^3 + 2t^2 - 3t + 4, v = 2t^3 + 5t^2 - 4t + 7, w = t^3 + 4t^2 + t + 2.$

Q.3 Let $F : R^4 \rightarrow R^3$ be linear map defined by (10)
 $F(x, y, z, t) = (x + 2y + 3z + 2t, 2x + 4y + 7z + 5t, x + 2y + 6z + 5t)$
Find a basis and dimension of image of F and Kernel of F.

OR

Q.3 Determine whether or not linear map F is non-singular. If not, find a nonzero (10)
vector V whose image is 0; otherwise find a formula for the inverse map.
 $F : R^3 \rightarrow R^3$ defined by $F(x, y, z) = (x + y + z, 2x + 3y + 5z, x + 3y + 7z)$

P. T. O.

- Q.4** Let G be the linear operator on R^3 defined by $G(x, y, z) = (2y + z, x - 4y, 3x)$. (10)
 Find the matrix representation of G relative to the basis
 $S = \{w_1, w_2, w_3\} = \{(1, 1, 1), (1, 1, 0), (1, 0, 0)\}$. Verify that $[G][v] = [G(v)]$ for
 any vector v in R^3 .

OR

- Q.4** Consider the following bases of R^2 (10)
 $E = \{e_1, e_2\} = \{(1, 0), (0, 1)\}$ and $S = \{u_1, u_2\} = \{(1, 3), (1, 4)\}$. Find the change of
 basis matrix P from P form the usual basis E to S . Find the change of basis of
 matrix Q from S back to E .

- Q.5** Let S consist of the following vectors in R^4 . (10)
 $u_1 = (1, 1, 0, -1)$, $u_2 = (1, 2, 1, 3)$, $u_3 = (1, 1, -9, 2)$, $u_4 = (16, -13, 1, 3)$. Show that S
 is coordinates of an arbitrary vector $v = (a, b, c, d)$ in R^4 relative to the basis S .

OR

- Q.5** Apply the Gram-Schmidt orthogonalization process to find an orthogonal basis (10)
 and then orthonormal basis for the subspace U of R^4 spanned by
 $v_1 = (1, 1, 1, 1)$, $v_2 = (1, 2, 4, 5)$, $v_3 = (1, -3, -4, -2)$.

- Q.6** Find the Eigen values and Eigen vectors of matrix A , Where (10)

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ -1 & 1 & 0 \end{bmatrix}$$

OR

- Q.6** Verify Cayley-Hamilton theorem for matrix A and use it to find A^4 and A^{-1} (10)

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 3 & 1 & 1 \\ 2 & 3 & 1 \end{bmatrix}$$

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