

**B.TECH SEM – VI (2007 COURSE) (ELECTRICAL ENGG.) :**

**SUMMER - 2018**

**SUBJECT: MODERN CONTROL SYSTEMS**

Day: **Friday**  
Date: **08/06/2018**

**S-2018-2717**

Time: **02.30 PM TO 05.30 PM**  
Max Marks: **80**

**N.B:**

- 1) Q. No. 1 and Q. No. 5 are **COMPULSORY**. Out of the remaining attempt any **TWO** questions from each section.
- 2) Both the sections should be written in **SEPARATE** answer books.
- 3) Draw neat labeled diagrams **WHEREVER** necessary.
- 4) Figures to the **RIGHT** indicate full marks.
- 5) Assume suitable data, if necessary.

**SECTION-I**

- Q.1**
- a) What is Jordan Canonical form? Explain with example. **(04)**
  - b) State Cayley Hamilton Theorem **(04)**
  - c) State three different types of nonlinearity .Sketch it with its input and output waveforms. **(06)**

- Q.2**
- a) Obtain state model by direct decomposition of system with transfer function **(07)**  
$$\frac{Y(s)}{U(s)} = \frac{(5s^2 + 6s + 8)}{s^3 + 3s^2 + 7s + 9}$$

- b) A system is represented by the following state and output equations. **(06)**  
Find poles of the system

$$\dot{X} = \begin{bmatrix} -3 & -2 \\ -1 & -2 \end{bmatrix} X + \begin{bmatrix} 1 \\ 1 \end{bmatrix} u(t), Y = [1 \quad 2] X.$$

- Q.3**
- a) Find controllability and observability of the state model **(08)**

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}, B = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, C = [1 \quad 1 \quad 1], D = 0.$$

- b) State Gilbert's test for controllability and observability. **(05)**

- Q4**
- a) Show different types of singular points and phase plane trajectory. **(06)**
  - b) Describe limit cycle phenomenon in phase plane method. **(07)**

**SECTION-II**

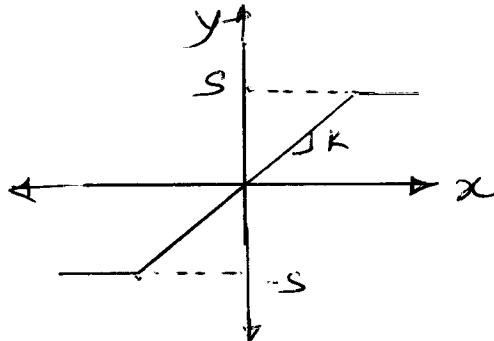
- Q5**
- a) Compare describing function method with phase plane method for stability analysis of non-linear systems. **(05)**

- b) Calculate z transform of **(05)**

(i)  $e^{-at} \sin \omega t$  (ii)  $a^n$

- c) State initial and final value theorem for z transform. **(04)**

- Q.6**
- a) Derive describing function for the following non-linearity. **(08)**



- b) Explain limit cycle using describing function analysis. **(05)**

**P.T.O.**

Q.7 a) Find the solution of (07)

$$c(k+2) + 3c(k+1) + 2 = r(k)$$

$$r(k) = 0 \text{ for } k = 0$$

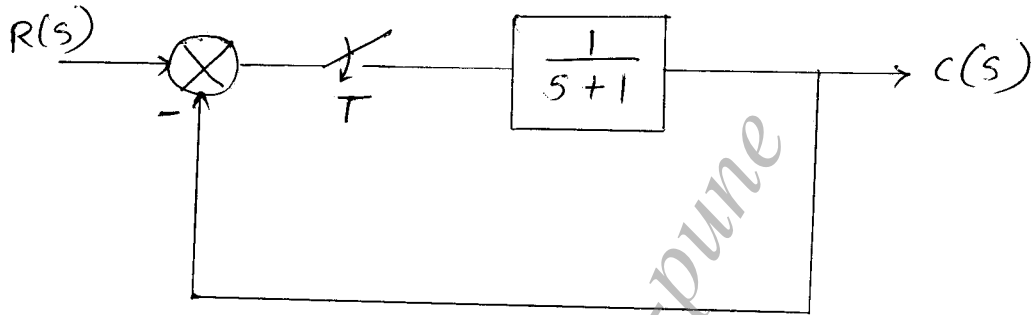
$$r(k) = 1 \text{ for } k > 1$$

$$c(1) = 0$$

b) Draw block diagram of discrete time system and explain function of each block. (06)  
State advantages of it over continuous time system.

Q.8 a) Solve  $2z^4 + 7z^3 + 10z^2 + 4z + 1 = 0$ . Use Jury's stability test. (06)

b) Write pulse transfer function  $C(z)/R(z)$  for the given system. (07)



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