

B.TECH. SEM -V BIO MEDICAL 2014 COURSE (CBCS) :

SUMMER - 2018

SUBJECT : INSTRUMENTATION & CONTROL SYSTEM

Day : **Monday**
Date : **21/05/2018**

S-2018-2375

Time : **10.00 AM TO 01.00 PM**
Max. Marks : 60

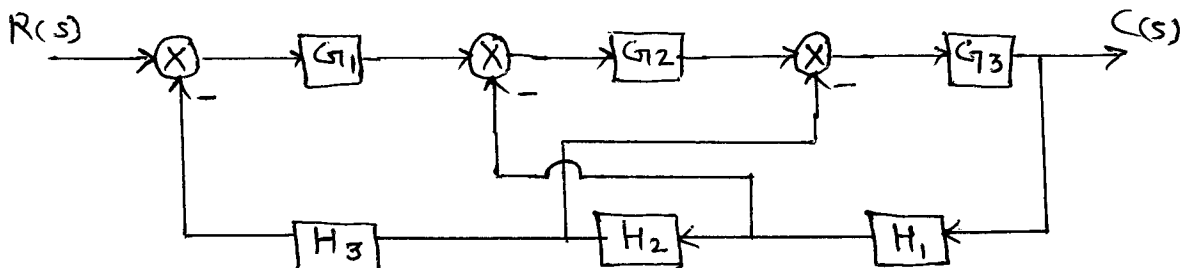
N. B. :

- 1) All questions are **COMPULSORY**.
- 2) Figures to the right indicate **FULL** marks.
- 3) Use of non programmable calculator is **ALLOWED**.
- 4) Draw neat and labeled diagram **WHEREVER** necessary.
- 5) Assume suitable data, if necessary.

Q.1 Define: (10)

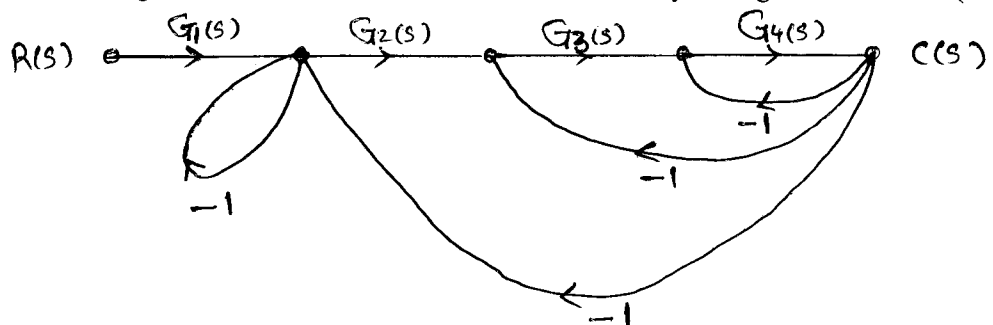
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|--------------------|------------|
| i) System | iii) Input |
| ii) Control system | iv) Output |

Also Find Transfer Function for the block diagram given below:



OR

Q.1 Using Masson's gain formula find 'Transfer Function' of system given below: (10)



Q.2 a) Explain construction and working principle of Thermocouple. (06)

b) A platinum thermometer has a resistance of 100Ω at 25°C . (04)

Find :

- i) its resistance at 65°C if the platinum has a resistance temperature coefficient of $0.00392/^\circ\text{C}$
- ii) If the thermometer has a resistance of 150Ω , calculate the temperature.

OR

Q.2 Describe the working principle of LVDT. What is residual voltage? Explain characteristics of LVDT. (10)

P. T. O.

- Q.3 a)** A unity feedback system has $G(s) = \frac{K(2s+1)}{s(4s+1)(s+1)^2}$, determine the value of 'K' if the steady state value of error to be less than 0.1 when an input $r(t) = 1 + 5t$ is applied. (06)

- b)** Find K_p , K_v and K_a for a unity feedback system with : (04)

$$G(s) = \frac{10(s+3)}{(s+1)(s^2+2s+2)}.$$

OR

- Q.3 a)** Derive expression for Unit step response of First order system. (06)

- b)** The closed loop transfer function of unity feedback system is given by : (04)

$$\frac{C(S)}{R(S)} = \frac{10}{s^2 + 4s + 5}. \text{ Determine : } \omega_n, \xi \text{ and } \%M_p.$$

- Q.4** Sketch the root locus for system given by : (10)

$$G(s)H(s) = \frac{K}{s(s+1)(s^2+4s+5)}.$$

OR

- Q.4 a)** State and explain Routh's stability. (06)

- b)** Explain effect of addition of poles and zeros on system stability. (04)

- Q.5** Draw Bode plot for the transfer function: (10)

$$G(s) = \frac{200(s+2)}{s(s^2+10s+100)}.$$

OR

- Q.5 a)** Describe frequency domain specifications. (06)

- b)** Discuss Nyquist stability criteria. (04)

- Q.6 a)** Describe PLC architecture in detail. (06)

- b)** Explain proportional [P] control action. (04)

OR

- Q.6** Write type of controllers. Describe On-Off controller in detail. (10)

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