## B.Tech. SEM -VII Mechanical 2014 Course (CBCS): SUMMER - 2019 SUBJECT: AUTOMATIC CONTROL SYSTEM

Saturday Time: 02.30 PM TO 05.30 PM Day: 11/05/2019 Date: Max Marks.: 60 S-2019-2835 N.B.: 1) All questions are **COMPULSORY**. 2) Figures to the right indicate FULL marks. 3) Assume suitable data, if necessary. 4) Use of non-programmable calculator is allowed. Q.1 Find range of 'K' so that system with the following equation will be stable. (10) $F(S) = S(S^2 + S + 1)(S + 4) + K = 0$ OR For a system with characteristic equation: Q.1 (10) $F(S) = S^6 + 3S^5 + 4S^4 + 6S^3 + 5S^2 + 3S + 2 = 0$ . Examine stability. 0.2 Explain following rules for block diagram reduction: (10)Blocks in parallel ii) Eliminate feedback loop iii) Shift summing point before the block **Q.2** Develop closed loop transfer function for the control system shown in figure -1. (10)Figure - 1 Q.3 Explain the following terms: (10)Delay time i) Peak time ii) iii) Peak overshoot Settling time iv) v) Steady state error OR Q.3 Explain the concept of state, state variable, state vector, state space and state (10) model. **Q.4** Write short notes on the following: (10)Inverting amplifier i) ii) Non-inverting amplifier OR Draw the neat circuit diagram of SAR type ADC & explain how it works. **Q.4** (10)Explain in detail working of PID control action. Q.5 (10)Differentiate between feedback and feed-forward control system. Q.5 (10)Draw and explain architecture of PLC. State the selection criteria of PLC. Q.6 (10)OR Write a short note on 'Timers' used in PLC. (10)Q.6